

ON BLOCK-QUASI-TRIDIAGONAL MATRICES

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Abstract - We intend to invert (and to study the eigenvalues of) block-quasi-tridiagonal matrices. We also mention ways for handling the problem of eigenvalues of a block-quasi-tridiagonal matrix and we obtain upper bounds for the spectral radius of a (certain) block-quasi-tridiagonal matrix which arises in the discretization of partial differential equations of elliptic type, self-adjoint case.

1. About the inversion of block-quasi-tridiagonal matrices

1.1 - In this section we interest us for inverting block-quasi-tridiagonal matrices, that is to say, matrices of the form

$$T = \begin{pmatrix} A_{11} & A_{12} & 0 & 0 & \dots & 0 & 0 & 0 & A_{1n} \\ A_{21} & A_{22} & A_{23} & 0 & \dots & 0 & 0 & 0 & 0 \\ & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots \\ 0 & 0 & 0 & 0 & \dots & 0 & A_{n-1,n-2} & A_{n-1,n-1} & A_{n-1,n} \\ A_{n1} & 0 & 0 & 0 & \dots & 0 & 0 & A_{n,n-1} & A_{nn} \end{pmatrix}$$

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where all blocks are of the same order and commute in pairs. Such matrices arise in the discretization of elliptic partial differential equations.

We need a result involving a matrix obtained from T by taking its determinant considering the (commuting) blocks as elements. Let $\Delta_T = \text{dev } T$ be such a matrix; Δ_T is the formal determinant of T . It is known that $\det \Delta_T = \det T$. This result allows us to manipulate only matrices of low order, when solving large systems of linear equations and, like in our case, inverting large block-matrices.

1.2 - To invert the matrix T we shall use an hybrid method: classical partitioning in four blocks plus a recurring procedure.

Let us partition and note as follows

$$T = \left(\begin{array}{c|c} \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} & \begin{array}{c} A_{1n} \\ 0 \\ \vdots \\ 0 \\ A_{n-1,n} \end{array} \\ \hline \begin{array}{c} A_{n1} \quad 0 \quad 0 \dots 0 \quad A_{n,n-1} \end{array} & A_{nn} \end{array} \right) = \left(\begin{array}{c|c} P & Q \\ \hline R & S \end{array} \right)$$

where P is a block-tridiagonal matrix.

It is known that the inverse of a matrix partitioned in that manner is

$$T^{-1} = \left(\begin{array}{c|c} K & L \\ \hline M & N \end{array} \right)$$

with the same partitioning and where

$$K = P^{-1} - P^{-1}QM, \quad M = -NRP^{-1}, \quad L = -P^{-1}QN \quad \text{and} \quad N = (S - RP^{-1}Q)^{-1}.$$

In this way we need only to invert two matrices: P and $(S - RP^{-1}Q)$. So we have to invert a large matrix P , with commuting blocks. For achieving this, one can use a recurring procedure. We obtain a matrix $P^{-1} = (X_{ij})$ partitioned in the same way as P and where the blocks X_{ij} also commute in pairs.

Let us denote by $P_{I(i,j)}$ the matrix obtained from P by replacing the j^{th} block-column with the matrix $\begin{pmatrix} 0 \\ \vdots \\ I \\ \vdots \\ 0 \end{pmatrix}$ \rightarrow i^{th} block-line.

Then, if we put

$$\Delta = \text{dev } P \quad \text{and} \quad n_{ij} = \text{dev } P_{I(i,j)}, \quad (i,j=1,2,\dots,n-1),$$

we obtain

$$X_{1j} = A^{-1} n_{1j}, \quad (i, j=1, 2, \dots, n-1)$$

1.3 - As we have seen, for inverting a block-quasi-tridiagonal matrix we need only to invert two matrices: $S-RP^{-1}Q$ and $\Delta := \text{dev } P$. But, in practice, we invert two matrices of the same order, instead of inverting a low order matrix $S-RP^{-1}Q$ and a high order matrix P . We remark that the matrices $S-RP^{-1}Q$ and Δ have the order of the original blocks A_{1j} .

2. About the eigenvalues of a (certain) block-quasi-tridiagonal matrix

In this section we interest us for the eigenvalue problem in block-quasi-tridiagonal matrices. Here we get upper bounds for the absolute value of the eigenvalues by using a matricial norm:

Upper bounds for the spectral radius of a block-quasi-tridiagonal matrix, which arise in the discretization of partial differential equations of elliptic type, self-adjoint case.

Given the matrix

$$T = \begin{pmatrix} A & B & 0 & 0 & \dots & 0 & 0 & B \\ B & A & B & 0 & \dots & 0 & 0 & 0 \\ 0 & B & A & B & \dots & 0 & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & B & A & B \\ B & 0 & 0 & 0 & \dots & 0 & B & A \end{pmatrix}$$

we look for upper bounds of $\rho(T)$, where $\rho(T)$ is the spectral radius of the matrix T , that is to say, $\rho(T) := \max |\lambda(T)|$, where $\lambda(T)$ is any eigenvalue of T .

We take the (scalar) norm $\|\cdot\|_1^{(1)}$, ($i=1, \infty$), of each block, so obtaining a matricial norm $M_1(T)$, ($i=1, \infty$). It is known, that $\rho(T) \leq \rho(M_1(T))$, ($i=1, \infty$). And it is also known that $\rho(A) \leq \|A\|_j$, ($j=1, \infty$), for any matrix A , and any (subordinate) matrix norm $\|\cdot\|_1$.

(1) For $B = (\beta_{ij}) \in M_{r,s}(K)$, $K=R$ (or C), we let

$$\|B\|_1 := \max_{j=1,2,\dots,s} \left\{ \sum_{i=1}^r |\beta_{ij}| \right\}, \quad \|B\|_\infty := \max_{i=1,2,\dots,r} \left\{ \sum_{j=1}^s |\beta_{ij}| \right\}.$$

Hence we have

$$\rho(T) \leq \|A\|_1 + 2 \|B\|_1, \quad (i=1, \infty)$$

a very simple upper bound for the eigenvalues of T .

Remark

The complete version of this paper is to appear in "Revista da Universidade de Coimbra".

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