

ON HOMOGENITY AND TRANSITIVITY
OF FIELDS OF GEOMETRIC OBJECTS

Jerzy Konderak

ABSTRACT. If σ is a field of geometric objects on a manifold M then we can associate with it a principal subbundle of $H^r(M)$. We show that (infinitesimal) homogeneity and (infinitesimal) transitivity of this subbundle are equivalent to some integral conditions for the Lie equations generated by σ .

I. INTRODUCTION

1. Let M be a differentiable manifold. In the present paper, manifolds, vector fields and so on always mean differentiable manifolds, differentiable vector fields and so on. Differentiability always means the differentiability of class C^∞ .

If U, V are open subsets of M then a diffeomorphism $\varphi : U \rightarrow V$ is called a local diffeomorphism of M . The set $\Gamma(M)$ of all local diffeomorphisms of M is a pseudogroup. By \mathcal{T}_M we shall denote a set of vector fields defined on open subsets of M .

We denote by $H^r(M)$ the set of all r -jets at 0 of diffeomorphisms of open neighbourhoods of 0 in \mathbb{R}^n onto open subsets of M . Let $\pi^r : H^r(M) \rightarrow M$ be the target projection. Then $H^r(M)$ is a principal fibre bundle with the

structure group L_n^r of all r -jets with the source and with the target at 0 of local diffeomorphisms of \mathbb{R}^n .

2. Let F denote a natural bundle from the category of n -dimensional manifolds (for the definition of the natural bundle see [7] or [8]). Differentiable sections of the bundle $\pi : F(M) \rightarrow M$ are called fields of geometric objects. We assume that F is of order r . It means that if U, V are n -dimensional manifolds and $\varphi, \psi : U \rightarrow V$ are diffeomorphisms such that $j_x^r \varphi = j_x^r \psi$ for a certain $x \in U$ then $F(\varphi)|_{\pi^{-1}(x)} = F(\psi)|_{\pi^{-1}(x)}$, that is $F(\varphi)$ and $F(\psi)$ are equal on the fiber of $\pi : F(U) \rightarrow U$ above the point x . Let $F_0 = \pi^{-1}(0)$, where $\pi : F(\mathbb{R}^n) \rightarrow \mathbb{R}^n$, be called a standard fibre of the bundle F .

If $X \in \underline{TM}$ then the flow of X induces a flow on $F(\text{dom}(X))$. The vector field on $F(\text{dom}(X))$ defined by this flow is called a complete lift of X and is usually denoted by $F(X)$ (cf. [9]).

A functor H^r which attaches to each n -dimensional manifold M the principal fibre bundle $H^r(M)$ is an example of a natural bundle. If $\varphi : N_1 \rightarrow N_2$ is an embedding of n -dimensional manifolds then $H^r(\varphi)(j_0^r f) = j_0^r(\varphi.f)$ where $j_0^r f \in H^r(N_1)$. The bundle H^r is of course of order r . A complete lift of $X \in \underline{TM}$ to the bundle $H^r(M)$ will be denoted by $H^r(X)$.

The concept of 'natural bundle' was introduced by A. Nijenhuis ([7]) as a modern approach to the classical theory of geometric objects (cf. [1]).

Let σ be a field of geometric objects on M . Then σ

induces a mapping $\tau_\sigma : H^r(M) \longrightarrow F_0$ such that

$$\tau_\sigma(j_0^r f) = F(f^{-1})\sigma(f(0)).$$

Let $\xi_0 \in \text{im } \tau_\sigma$. We assume that the set $E = (\tau_\sigma)^{-1}(\xi_0)$ is a principal subbundle of $H^r(M)$. It is easy to see that this is equivalent to the following fact: for each $x, y \in M$ there exists $\varphi \in \Gamma(M)$ such that $F(\varphi)\sigma(x) = \sigma(y)$. In the other words one can say that σ is 0-deformable (cf. [10]). Concerning fields of geometric objects one usually assumes that they are 0-deformable. The bundle E is not uniquely determined by σ and it also depends on the choice of an element of F_0 . Although we fix the bundle E , all the results are true for all subbundles of $H^r(M)$ induced by σ .

II. LIE EQUATIONS ASSOCIATED WITH THE FIELD OF GEOMETRIC OBJECTS.

We shall recall some facts from the theory of Lie equations. These facts will be applied in the third part of this paper. The basic definitions of the theory of Lie equations one can find in [2], [3], [4].

1. There are given the natural bundle F of order r and the field of geometric objects σ on M (cf. I.3). Let

$$\Pi^r(M) = \{j_x^r \varphi : \varphi \in \Gamma(M) \text{ and } x \in \text{dom } \varphi\}.$$

Then $\Pi^r(M)$ is a Lie groupoid (cf. [6]). Let now

$$\Pi^r(\sigma) = \{j_x^r \varphi \in \Pi^r(M) : F(\varphi)\sigma(x) = \sigma(\varphi(x))\}.$$

With the field σ we associated also the bundle E .

Lemma II.1. The following equality holds

$$\Pi^r(\sigma) = \{p' \cdot p^{-1} : p, p' \in E\}$$

where $(j_0^r g) \cdot (j_0^r f)^{-1} = j_x^r (g \cdot f^{-1})$ for $j_0^r f, j_0^r g \in H^r(M)$ and $x = f(0)$.

Proof. Let $j_x^r \varphi \in \Pi^r(\sigma)$ and $y = \varphi(x)$. Let $j_0^r f \in E_x$ then $\tau_\sigma(j_0^r(\varphi \cdot f)) = F((\varphi \cdot f)^{-1})\sigma(y) = F(f^{-1})F(\varphi^{-1})\sigma(y) = F(f^{-1})\sigma(x) = \xi$. so $j_0^r(\varphi \cdot f) \in E$. Hence we get that $j_x^r \varphi = j_0^r(\varphi \cdot f) \cdot (j_0^r f)^{-1}$ and both jets on the right side of this equation belong to E . Since then $j_0^r \varphi \in \{p' \cdot p^{-1} : p', p \in E\}$.

Let now $j_x^r \psi = j_x^r (h \cdot g^{-1})$ where $j_0^r h, j_0^r g \in E$. Then $F(\psi)\sigma(x) = F(h \cdot g^{-1})\sigma(x) = F(h)F(g^{-1})\sigma(g(0)) = F(h)\tau_\sigma(j_0^r g) = F(h)\xi_0 = F(h)\tau_\sigma(j_0^r h) = F(h)F(h^{-1})\sigma(h(0)) = \sigma(h(0))$. Hence we get that $F(\psi)\sigma(x) = \sigma(\psi(x))$.

Therefore by [6] we get that $\Pi^r(\sigma)$ is a Lie groupoid because it is associated with the bundle E .

A local diffeomorphism φ is called a local solution of the non-linear Lie equation $\Pi^r(\sigma)$ iff for each $x \in \text{dom } \varphi$ $j_x^r \varphi \in \Pi^r(\sigma)$; $\Pi^r(\sigma)$ is called completely integrable iff for each $\eta \in \Pi^r(\sigma)$ there exists a local solution φ such that $j_x^r \varphi = \eta$ for a certain $x \in \text{dom } \varphi$.

2. Let now $R^r(\sigma) = \{j_x^r X : X \in \underline{TM}, x \in \text{dom } X \text{ and } (L_X \sigma)_x = 0\}$. A. Zajtz proved that $R^r(\sigma)$ is a linear Lie equation and the

canonical projection $\text{pr} : R^r(\sigma) \rightarrow TM$ is surjective where $\text{pr}(j_x^r X) = X_x$. Here $L_X \sigma$ denotes a Lie derivative for a field of geometric objects (cf. [9], [10]).

A vector field $X \in \underline{TM}$ is called a local solution of $R^r(\sigma)$ iff for each $x \in \text{dom}(X)$ we have $j_x^r X \in R^r(\sigma)$. The linear Lie equation $R^r(\sigma)$ is called completely integrable iff for each $\eta \in R^r(\sigma)$ there exists a local solution X such that $j_x^r X = \eta$ for a certain $x \in \text{dom}(X)$.

Lemma II.2. The following conditions are equivalent:

- i). $(L_X \sigma)_x = 0$;
- ii). $H^r(X)_z \in T_z E$ where $z \in E_x$ and $H^r(X)$ is a complete lift of the vector field X to the bundle $H^r(M)$.

Proof. We have the following canonical mapping $\Phi : H^r(M) \rightarrow F(M)$, where $\Phi(j_0^r f) = F(f)\xi_0$ for $j_0^r f \in H^r(M)$. It was shown that Φ is a differentiable fibre mapping covering the identity mapping on M . (cf. [10]). It is easy to see that $\Phi^{-1}(\sigma(M)) = E$. Hence $TE = (d\Phi)^{-1}(T\sigma(M))$. Let us also remark that if Z is a vector field on M then $H^r(Z)$ is projectable on $F(Z)$ via Φ .

Let first assume that $(L_X \sigma)_x = 0$. It means that $d_x \sigma(X_x) = F(X)_{\sigma(x)}$ and $F(X)_{\sigma(x)} \in T_{\sigma(x)} \sigma(M)$. We have also that $d_z \Phi(H^r(X)_z) = F(X)_{\sigma(x)}$. Hence $H^r(X)_z \in T_z E$ and the implication i). \Rightarrow ii). is proved.

Let now assume that $H^r(X)_z \in T_z E$. Therefore $d_z \Phi(H^r(X)_z) \in T_{\sigma(x)} \sigma(M)$ and moreover $F(X)_{\sigma(x)} \in T_{\sigma(x)} \sigma(M)$.

Let us notice that the canonical projection $d_{\sigma(x)}\pi :$

$: T_{\sigma(x)}\sigma(M) \longrightarrow T_x M$ is an isomorphism and $X_x = d_{\sigma(x)}\pi(F(X)_{\sigma(x)}) = d_{\sigma(x)}\pi(d_x\sigma(X_x))$. Hence $F(X)_{\sigma(x)} = d_x\sigma(X_x)$ and this ends the proof of the implication ii). \Rightarrow i).

III. HOMOGENITY AND TRANSITIVITY OF FIELDS OF GEOMETRIC OBJECTS.

In this section we suggest notions of homogeneity and transitivity for fields of geometric objects. We also do this in the infinitesimal case. Then we relate this notions to the similar properties of E .

1. We shall use the following notation:

$$A(\sigma) = \{\varphi \in \Gamma(M) : x \in \text{dom}\varphi \Rightarrow F(\varphi)\sigma(x) = \sigma(\varphi(x))\}$$

$$(\sigma) = \{X \in \underline{TM} : \varphi_t \in A(\sigma) \text{ where } \varphi_t \text{ is the flow of } X\}.$$

Definition III.1. We shall call σ homogenous iff $A(\sigma)$ acts transitively on M and infinitesimally homogenous iff for every $x \in M$ and $v \in T_x M$ there exists $X \in A(\sigma)$ such that $X_x = v$.

Definition III.2. We shall call σ transitive iff for each $\eta \in \Pi^r(\sigma)$ there exists $\varphi \in A(\sigma)$ such that $j_x^r \varphi = \eta$ where x is a source of η . We shall call σ infinitesimally transitive iff for each $\zeta \in R^r(\sigma)$ there exists $X \in A(\sigma)$ such that $j_y^r X = \zeta$ where y is a source of ζ .

The sets $A(\sigma)$ and $A(\sigma)$ can be described in the following way:

Lemma III.3. If σ is a 0-deformable field of geometric objects then

- a). $A(\sigma)$ is a set of solutions of $\Pi^r(\sigma)$;
- b). $A(\sigma)$ is a set of solutions of $R^r(\sigma)$.

Proof: If $\varphi \in \Gamma(M)$ then φ is a local solution of $\Pi^r(\sigma)$ iff for each $x \in \text{dom} \varphi$ $j_x^r \varphi \in \Pi^r(\sigma)$. This is equivalent to the fact that for each $x \in \text{dom} \varphi$ $F(\varphi)\sigma(x) = \sigma(\varphi(x))$. Hence φ is a local solution of $\Pi^r(\sigma)$ iff $\varphi \in A(\sigma)$. So a). is proved.

Let $X \in A(\sigma)$ and $x \in \text{dom} X$ and let φ_t denote the flow of X then $F(\varphi_t)\sigma(x) = \sigma(\varphi_t(x))$. Hence $F(X)_{\sigma(x)} = d_x \sigma(X_x)$. This means that $(L_X \sigma)_x = 0$ because the Lie derivative of the field of geometric objects can be expressed in the following way $(L_X \sigma)_x = d_x \sigma(X_x) - F(X)_{\sigma(x)}$ (cf. [9],[10]). Therefore X is a solution of $R^r(\sigma)$.

Let now Y be a solution of $R^r(\sigma)$ then it generates the field $F(Y)$ on $F(M)$. Since for every $x \in \text{dom} Y$ $F(Y)_{\sigma(x)} = d_x \sigma(Y_x)$ then $F(Y)|_{\sigma(\text{dom} Y)}$ is a vector field on $\sigma(\text{dom} Y)$. If ψ_t is a flow of Y then $F(\psi_t)\sigma(x) \in \sigma(\text{dom} Y)$. Hence $F(\psi_t)\sigma(x) = \sigma(\psi_t(x))$ and $Y \in A(\sigma)$. This ends the proof of b).

From lemma III.3 we get immediately the following corollary

Corollary III.4.

- i). The field σ is homogenous iff for each $x, y \in M$ there exists φ a local solution of $\Pi^r(\sigma)$ such that $\varphi(x) = y$;

ii). σ is infinitesimally homogenous iff for each $x \in M$ and $v \in T_x M$ there exists X a local solution of $R^r(\sigma)$ such that $X_x = v$;

iii). σ is transitive iff $H^r(\sigma)$ is completely integrable;

iv). σ is infinitesimally transitive iff $R^r(\sigma)$ is completely integrable.

2. With the principal fibre bundle E we can associate the following sets:

$$A(E) = \{ \varphi \in \Gamma(M) : H^r(\varphi)E|_{\text{dom}\varphi} \subset E \} ,$$

$$A(E) = \{ X \in \underline{TM} : \varphi_t \in A(E) \text{ where } \varphi_t \text{ is the flow of } X \} .$$

The bundle E is called homogenous iff for each $x, y \in M$ there exists $\varphi \in A(E)$ such that $\varphi(x) = y$; E is called transitive iff for each $z_1, z_2 \in E$ there exists $\psi \in A(E)$ such that $H^r(\psi)z_1 = z_2$. The bundle E is called infinitesimally homogenous iff for each $x \in M$ and each $v \in T_x M$ there exists $X \in A(E)$ such that $X_x = v$; E is called infinitesimally transitive iff for each $z \in E$ and each $X^r \in T_z E$ there exists $X \in A(E)$ such that $H^r(X)_z = X^r$. Such meanings of (infinitesimal) homogeneity and (infinitesimal) transitivity are used for instance by P. Molino [5].

Lemma III.5. If E is a principal fibre bundle associated with the 0-deformable field of geometric objects σ then $A(\sigma) = A(E)$ and $A(\sigma) = A(E)$.

Proof. It is enough to prove that $A(\sigma) = A(E)$.

Let $\varphi \in A(\sigma)$ then it is easy to notice that $\tau_\sigma \cdot H^r(\varphi) = \tau_\sigma \circ H^r(\text{dom} \varphi)$. If $z \in E|_{\text{dom} \varphi}$ then $\tau_\sigma(H^r(\varphi)z) = \tau_\sigma(z) = \xi_0$. Hence $H^r(\varphi)E|_{\text{dom} \varphi} \subset E$ and $\varphi \in A(E)$.

On the other hand let $\psi \in A(E)$ and let $j_0^r f \in E_x$ where $x \in \text{dom} \psi$. It implies that $\tau_\sigma(H^r(\psi)j_0^r f) = \tau_\sigma(j_0^r f) = \xi_0$. From the definition of τ_σ we get that $F(f^{-1} \cdot \psi^{-1})\sigma\psi(x) = F(f^{-1})\sigma(x)$. Hence $F(\psi^{-1})\sigma\psi(x) = \sigma(x)$ and $\psi \in A(\sigma)$. That ends the proof.

In the following proposition we compare (infinitesimal) homogeneity and (infinitesimal) transitivity of the bundle E and the field of geometric objects σ .

Proposition III.6. If σ is a 0-deformable field of geometric objects and E is a principal fibre bundle generated by σ then

- i) σ is homogenous iff E is homogenous;
- ii) σ is infinitesimally homogenous iff E is infinitesimally homogenous;
- iii) σ is transitive iff E is transitive;
- iv) σ is infinitesimally transitive iff E is infinitesimally transitive.

Proof. The first condition is a simple consequence of Lemma III.5.; ii). one can easily get from lemma II.2. Similarly iv). easily follows from lemma II.2. and lemma III.5.

To prove iii). it is enough to notice that if $z_1, z_2 \in E$ and $\varphi \in \Gamma(M)$ then $H^r(\varphi)z_1 = z_2$ iff $j_x^r \varphi = z_2 \cdot z_1^{-1}$ where x

is the source of z_1 . Hence the third equivalence is an easy consequence of lemma II.1. and lemma III.5.

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Instytut Matematyki
Uniwersytet Jagielloński
Ul. Reymonta 4, 30-059 Kraków
POLAND