

Note on the Unavailability of Code and Documentation

Dear Tribunal,

I would like to inform you that the development of the project presented in this thesis, titled:

"Stable Reinforcement Learning for Humanoid Locomotion"

was carried out entirely during my internship at **PAL Robotics S.L.** As such, all the code and internal documentation was developed within the company and are considered confidential, since they fall under PAL Robotics' intellectual property.

Because of this, I'm not allowed to share the source code or internal documentation as part of this submission. These materials are owned by the company and are protected by their internal policies regarding copyright and confidentiality.

I appreciate your understanding, and I remain available to clarify any aspect of the work or my contributions to the project and share any part of the code, within the limits of what I'm allowed to disclose.

Best regards,
Roger Perramon Marquès
30/06/2025